



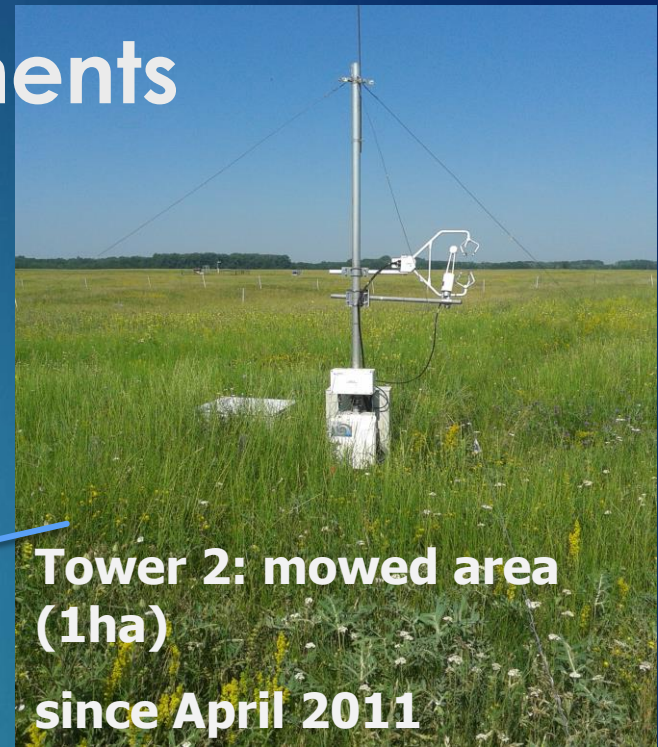
Estimation of spatial biomass distribution of a grassland using UAV based multispectral imagery

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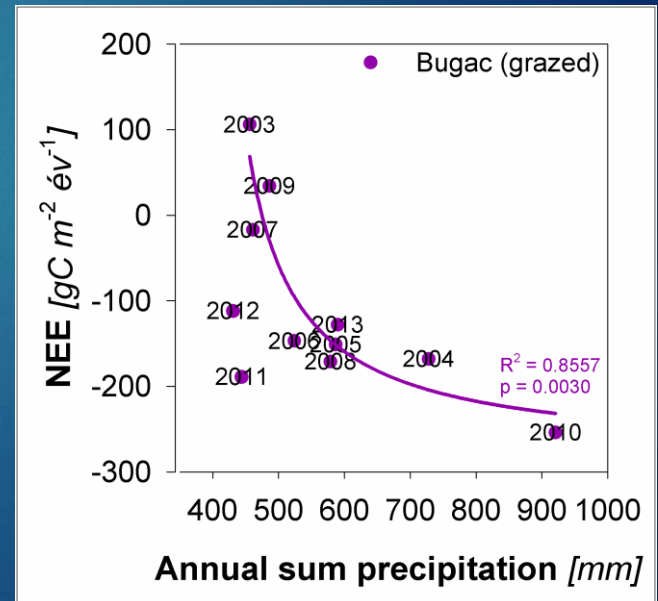
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²MTA-SZIE, PLANT ECOLOGY RESEARCH GROUP

Eddy covariance measurements since 2002

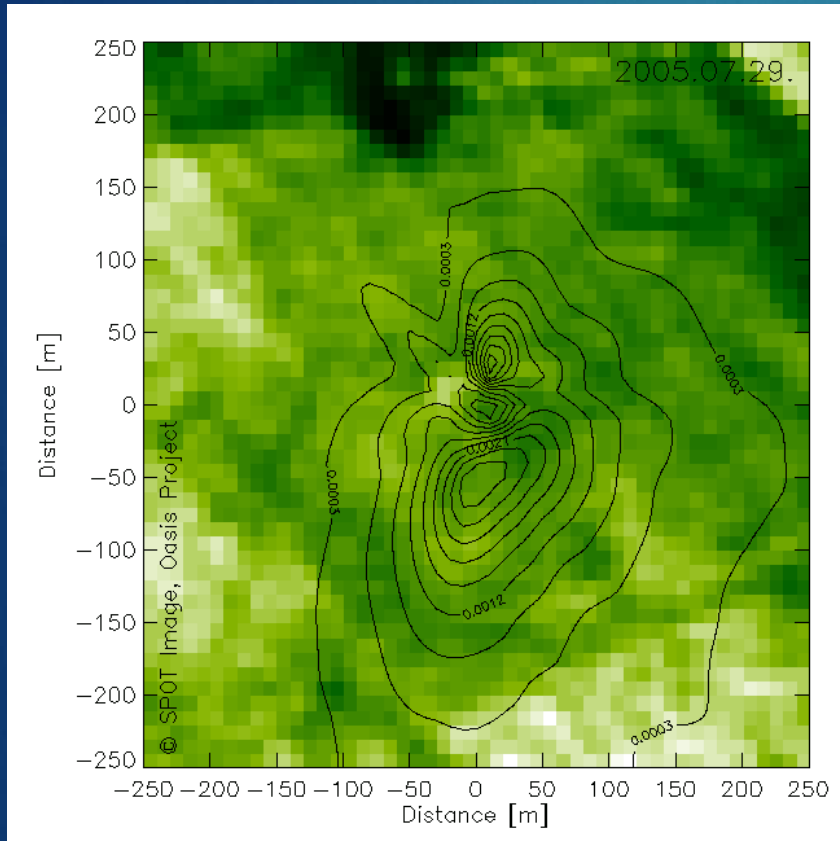


Tower 2: mowed area (1ha) since April 2011

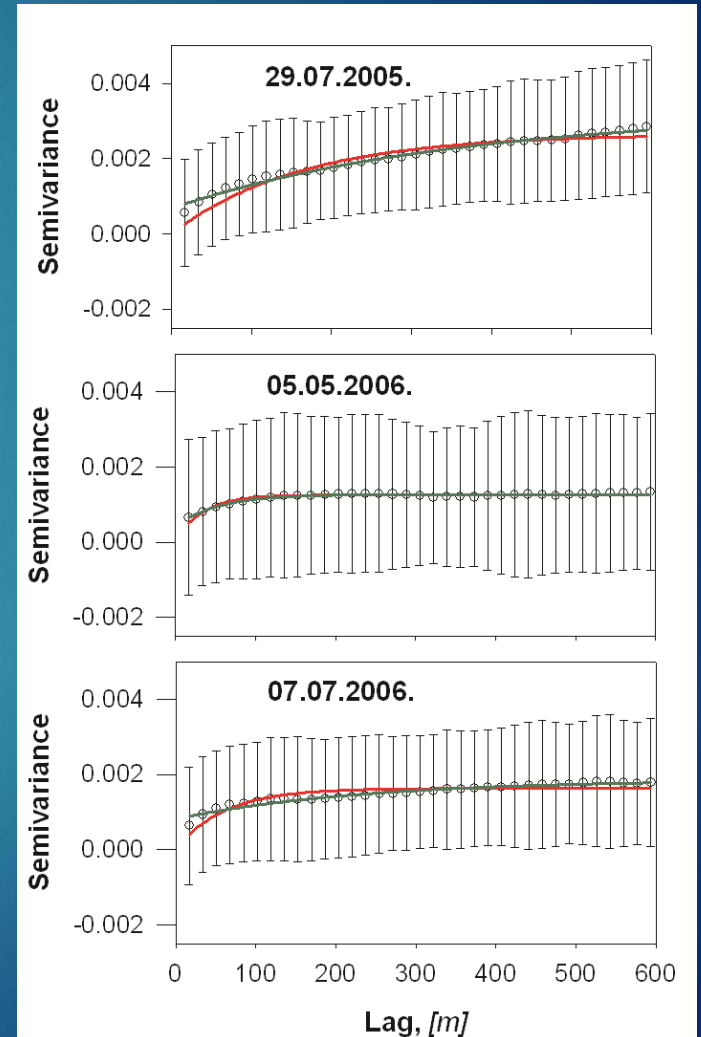


Highly diverse grassland: more than 100 species

Previous investigations... spaceborn hyperspectral image



SPOT NDVI
1km x 1km area
10m pixel size



UAV based multispectral imaging 2014

Mikrokopter XL



14 flights in May-September 2014



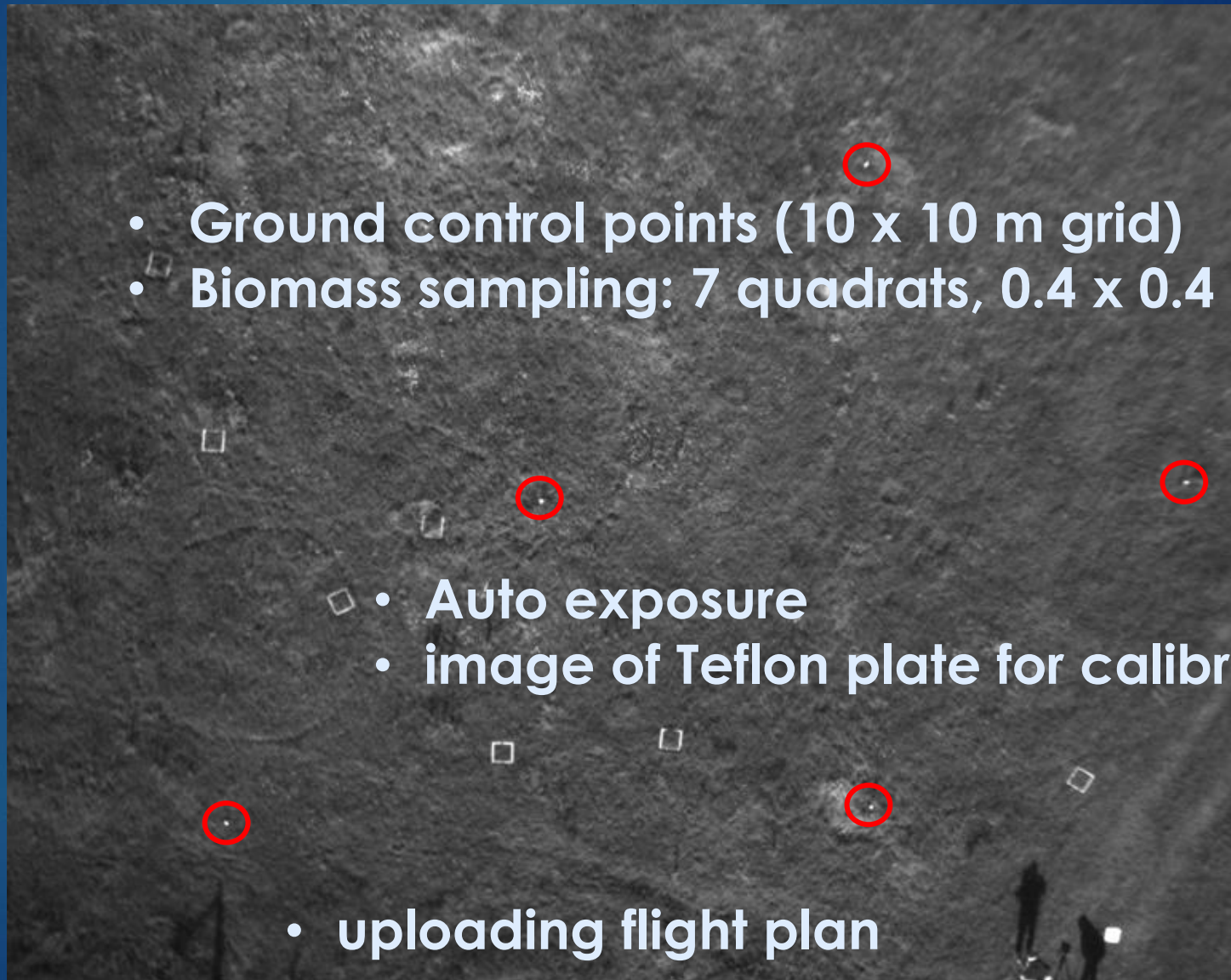
Tetracam, Mini MCA

- 550 nm
- 680 nm
- 800 nm
- 970 nm

planned upgrade

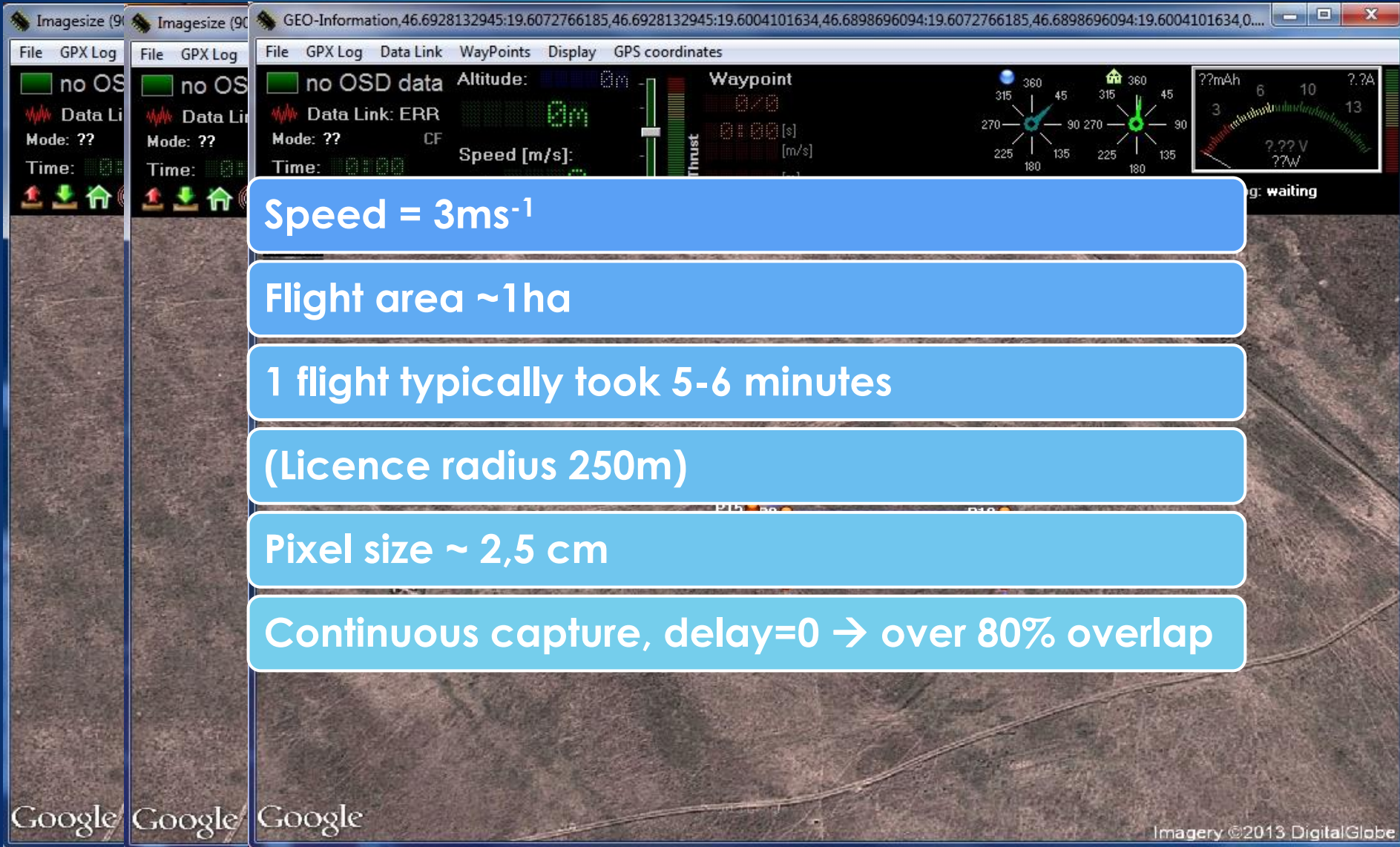
- 740 nm
- ILS
- camera calibration

Prior to flight



- Ground control points (10 x 10 m grid)
- Biomass sampling: 7 quadrats, 0.4 x 0.4 m
- Auto exposure
- image of Teflon plate for calibration
- uploading flight plan

Routes



The screenshot displays a flight software interface with a map background and several data readouts. The top bar shows the title 'GEO-Information, 46.6928132945; 19.6072766185, 46.6928132945; 19.6004101634, 46.6898696094; 19.6072766185, 46.6898696094; 19.6004101634, 0...'. The main interface includes a menu bar with 'File', 'GPX Log', 'Data Link', 'WayPoints', 'Display', and 'GPS coordinates'. Below the menu, there are several status indicators: 'no OSD data', 'Data Link: ERR', 'Mode: ??', 'Time: 00:00', 'Altitude: 0m', 'Speed [m/s]: 0', 'Waypoint 0/0', '0:00 [s]', and '0 [m/s]'. On the right side, there are two circular gauges showing heading and a small graph showing battery status. The bottom of the interface shows a map with a flight path and a 'Google' logo.

Speed = 3ms^{-1}

Flight area $\sim 1\text{ha}$

1 flight typically took 5-6 minutes

(Licence radius 250m)

Pixel size $\sim 2,5\text{ cm}$

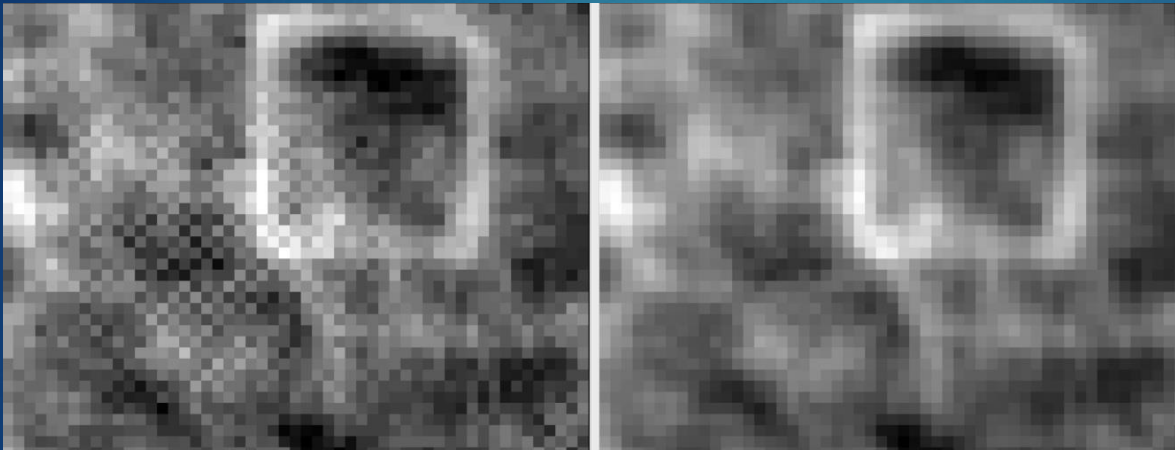
Continuous capture, delay=0 \rightarrow over 80% overlap

Flights – 2014

DST (UTC+2)	grazed1		grazed2		mowed	
	Start	end	start	end	start	end
6 May 2014	11:36	11:39				
9 May 2014	13:23	13:27			12:17	12:22
28 May 2014	08:05	08:08	08:52	08:56	08:21	08:26
4 June 2014	08:53	08:57	14:27	14:36	09:06	09:11
19 June 2014	10:11	10:13	10:22	10:26		
2 July 2014	08:31	08:34	09:04	09:09	09:29	09:34
25 July 2014	09:02	09:06	09:26	09:31	10:30	10:35
12 August 2014	14:13	14:16				
18 August 2014	09:35	09:38	09:45	09:49	10:27	10:32
29 August 2014	10:03	10:06	10:13	10:17	10:55	11:01
9 September 2014	12:02	12:06	12:11	12:15	12:58	13:03
24 September 2014	10:45	10:49	10:56	11:00	11:36	11:45

Data processing

Noise reduction with convolution filter



0	1	0
1	3	1
0	1	0

CONVOLUTION MATRIX:

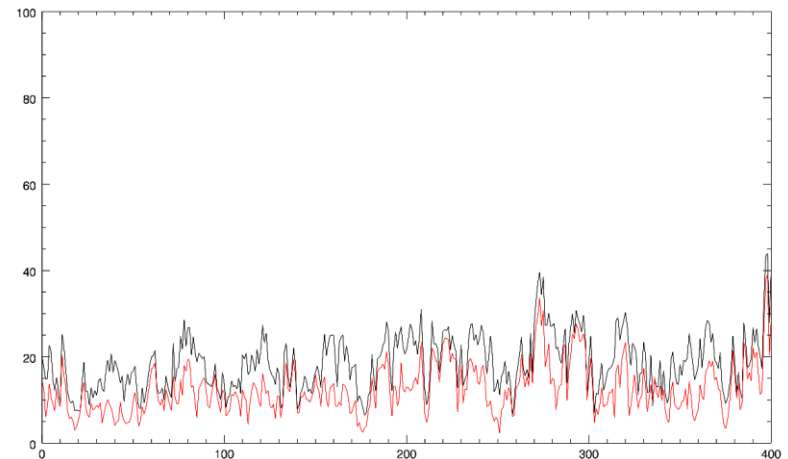
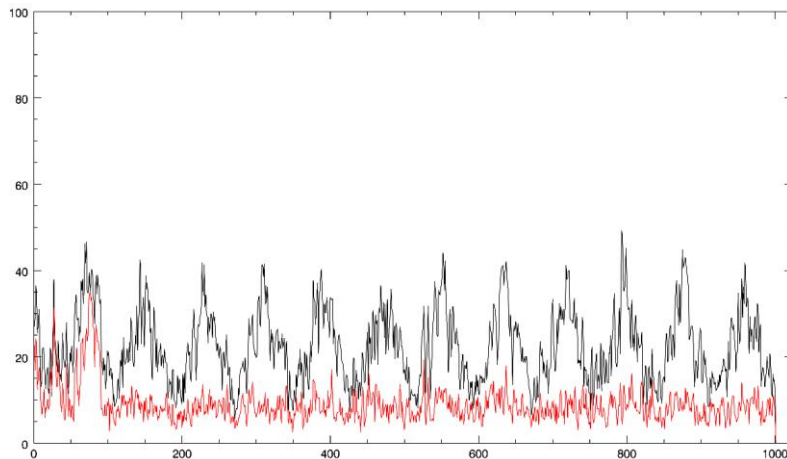
$$New(x, y) = \frac{\sum_{i,j=1}^3 CM(i, j) * Original(x + 1 - i, y + 1 - j)}{\sum CM}$$

Data processing

Noise reduction with convolution filter

3x3 Standard deviation
(teflon plate)

3x3 Standard deviation
(vegetation)

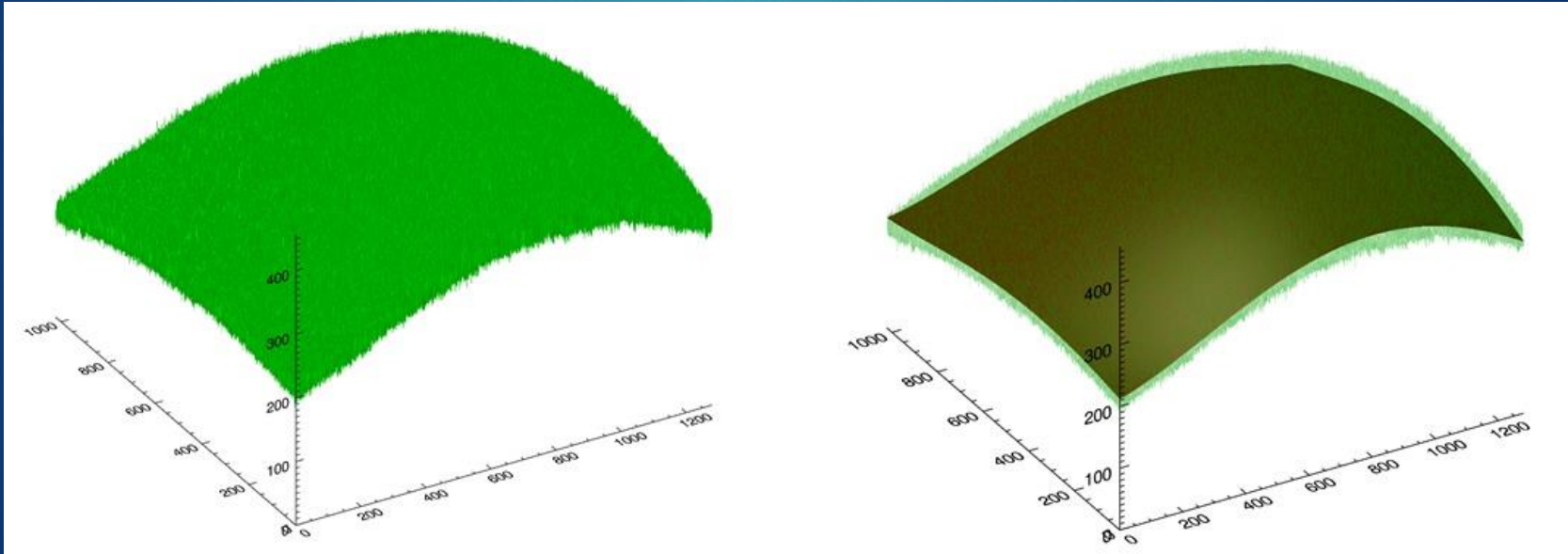


Black: original image Red: filtered image

Data processing

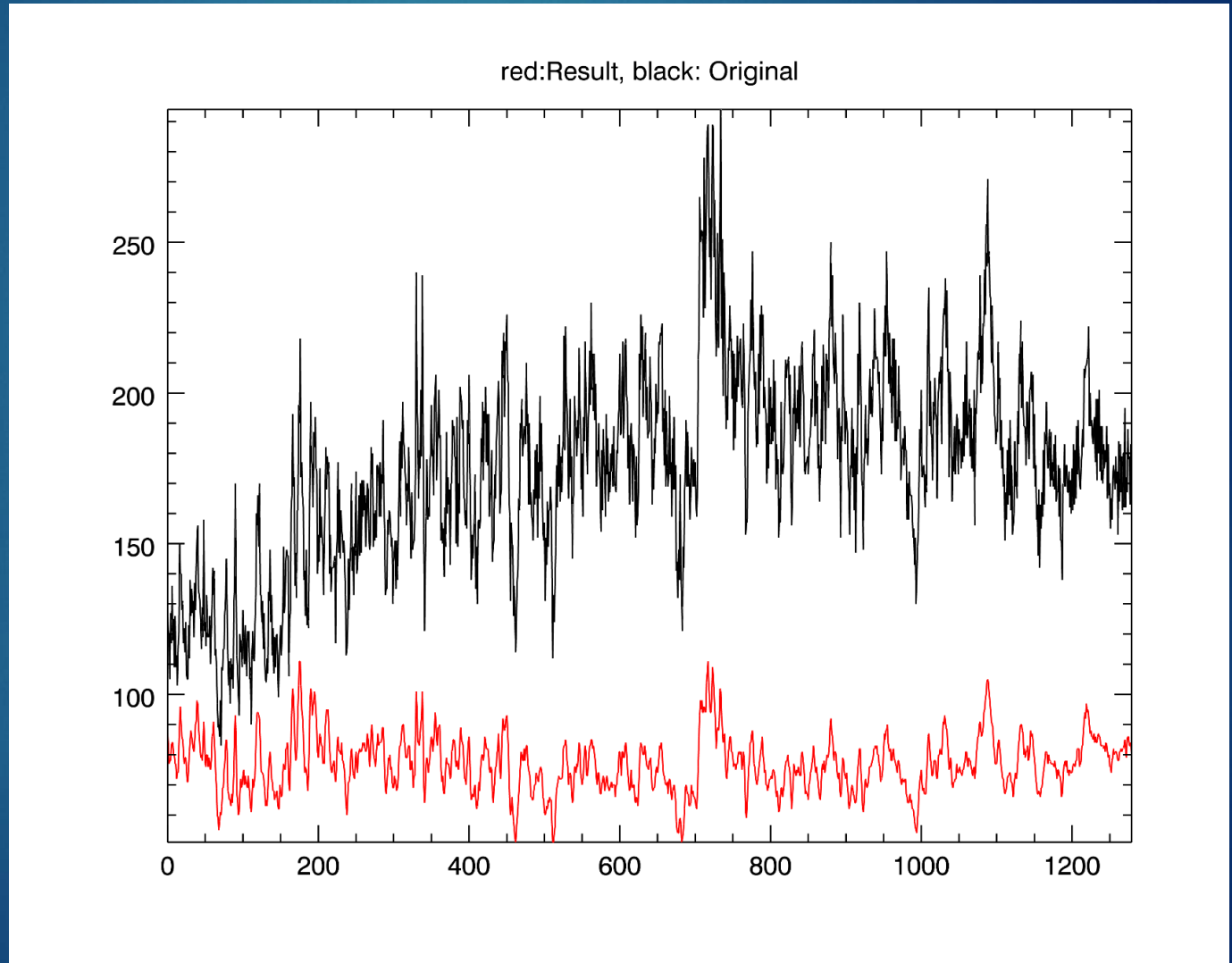
Vignetting

- ▶ 3D function surface
- ▶ Surface was calculated from a photo taken from a white surface



Data processing

Vignetting



Data processing

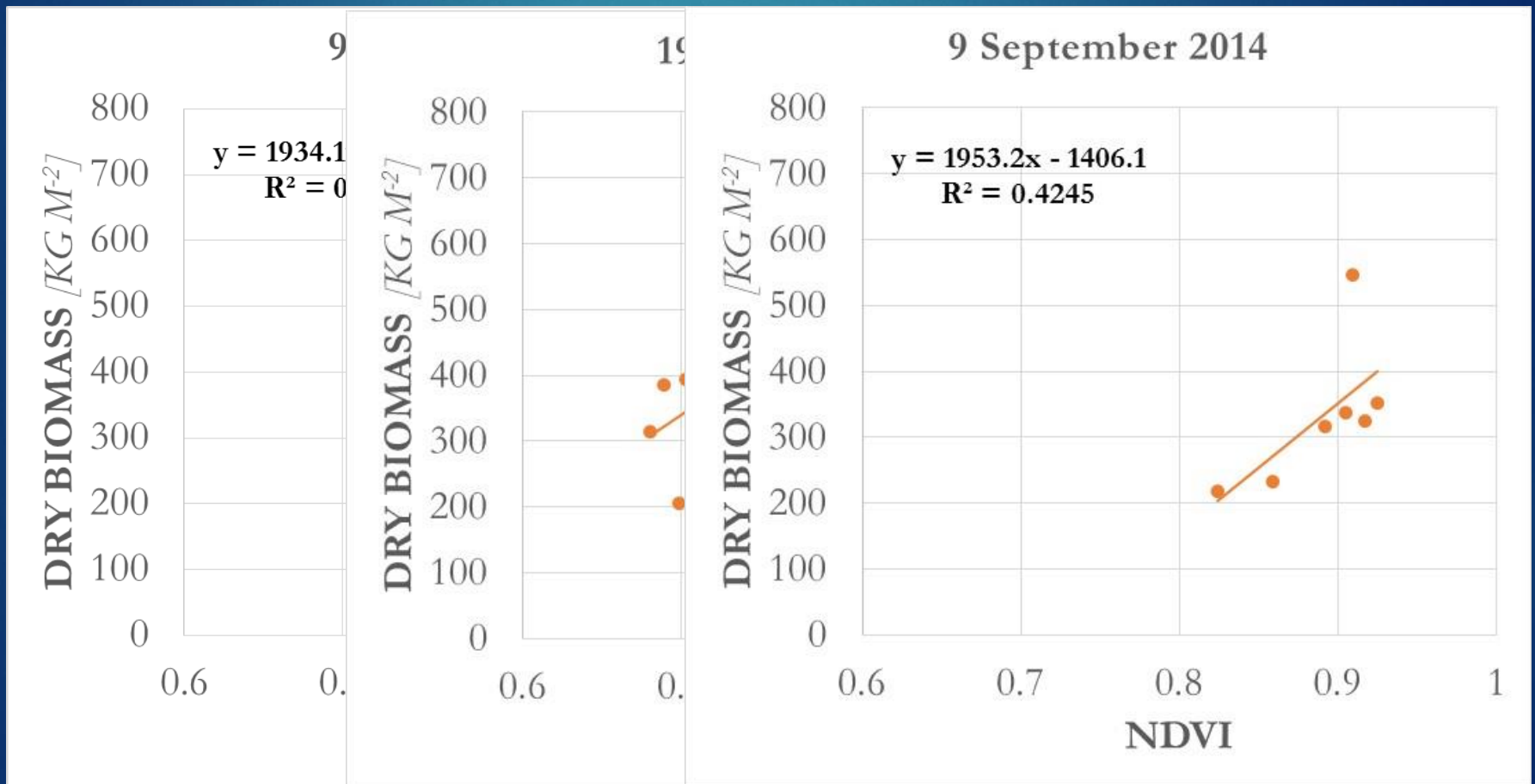
Reflectance calculations

- ▶ Variable (automatic) exposure time during flights and when taking image of the Teflon plate → normalizing all exposure times to that of the calibration pictures to get comparable reflectance values for the different images

Results

NDVI

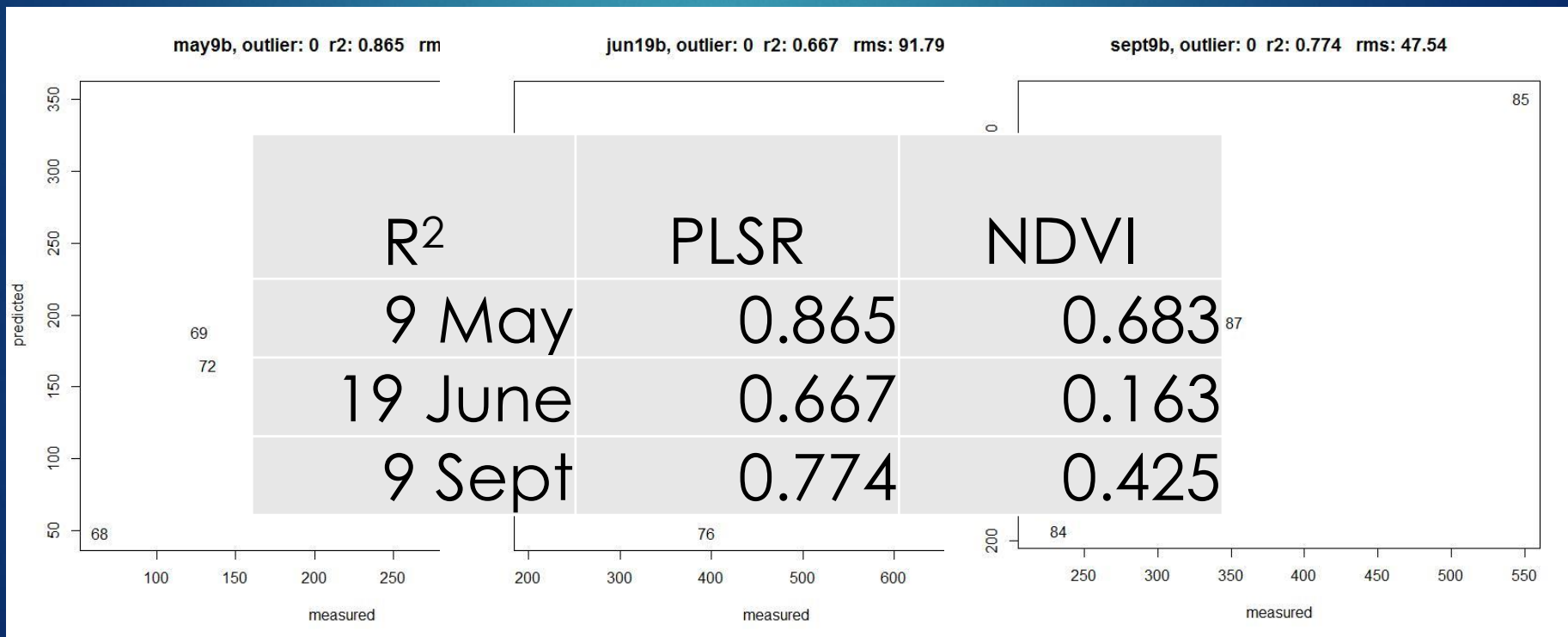
NDVI was calculated from the bands 680 and 800 nm.



Results

Partial least squares regression

- ▶ Use of partial least squares regression model (plsr in R) to use the available channels (4 cameras) simultaneously to explain larger part of biomass variance.
- ▶ Input: 4 reflectance values and biomass as dependent variable



Further possible steps when using PLSR:

- ▶ Search for outliers: leaving out one of the seven calibration quadrats (BSQ) leading to the largest increase in PLSR's R^2 .
- ▶ Inclusion of standard deviation (of a ROI around the pixel) in PLSR to increase the number of input variables. (assumption: larger standard deviations may arise from higher variation of biomass within the BSQ and/or shadows due to size differences of plants).
- ▶ Test (validation) of the plsr approach: not finished yet, first results are disappointing. Using the "leave one out" method results in large RMSE

Conclusions

- ▶ Flights at wind speeds less than 5 ms^{-1} - requires early flights during the day \leftrightarrow shadows
- ▶ Flights during noon hours \leftrightarrow windy and cloudy conditions.
- ▶ Auto exposure (master) is needed to avoid over or under exposition of the master.
- ▶ Problems with the exposure times (some of the channels may be over or underexposed compared to the master) – adjusting the relative exposure times to avoid over or under exposition AND to increase the dynamic range. This may decrease the weight of the black noise significantly.
- ▶ Use of ILS for to get direct reflectance values
- ▶ Increasing the number of biomass sampling quadrats (ground control) is not really feasible.
- ▶ Use of PLSR: underway, results are generally better than those from simple NDVI indices – validation of regression is the next step.

**Thank you for your
attention!**

Dark noise filtering

after Kelcey and Lucier, Remote Sens. 2012,4,1462-1493

Average of 125 pictures (10bit) taken inside a dark box

