

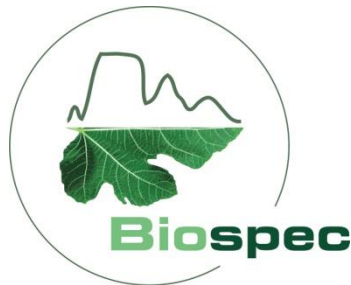
# Hyperspectral airborne imagery for carbon flux modelling in a wood-pasture ecosystem

*Javier Pacheco-Labrador*

*PhD student, Environmental Remote Sensing and  
Spectroscopy Laboratory (SpecLab – CSIC)*

# SUMMARY

1. Introduction
2. Methods
3. Estimation of Sun Induced Fluorescence
4. Results
5. Preliminar discussion



# 1. Introduction

- Carbon fluxes modeled from remote sensors (Gamon et al. 2006 and 2011)
  - **WHAT** is measured?
    - Mix of different covers
  - From **WHERE** does the fluxes come from?
    - Spatial aggregation of spectral variables and flux data
  - **WHEN** spectral and flux variables are related?
    - Temporal aggregation of flux data and spectral variables
    - What do spectral variables mean?



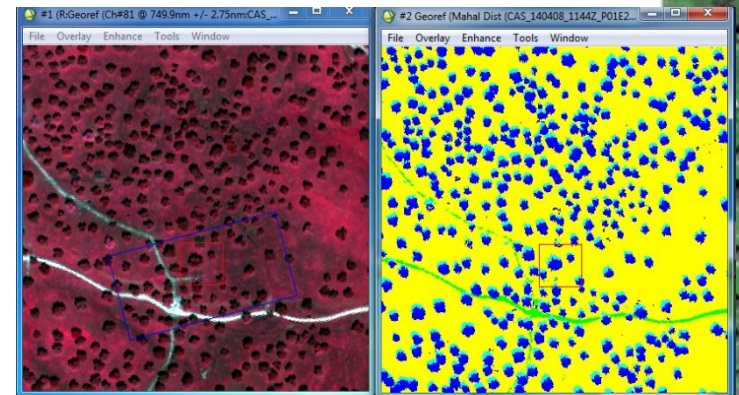
# 1. Introduction

- To address these questions
  - High spatial resolution
  - Different strategies to select the area from where spectral data are related with the flux data
  - Different time windows from where flux data are related with spectral variables
  - Use different models to relate the variables



## 2. Methods

- 8 Airborne hyperspectral images
  - CASI (VNIR sensor, INTA)
  - Majadas del Tiétar site
    - Grass – pasture ecosystem
    - 1-3 EC towers
  - 4 different dates
  - Supervised classification
    - Grass / Trees
    - Soil-roads / Shadow-water

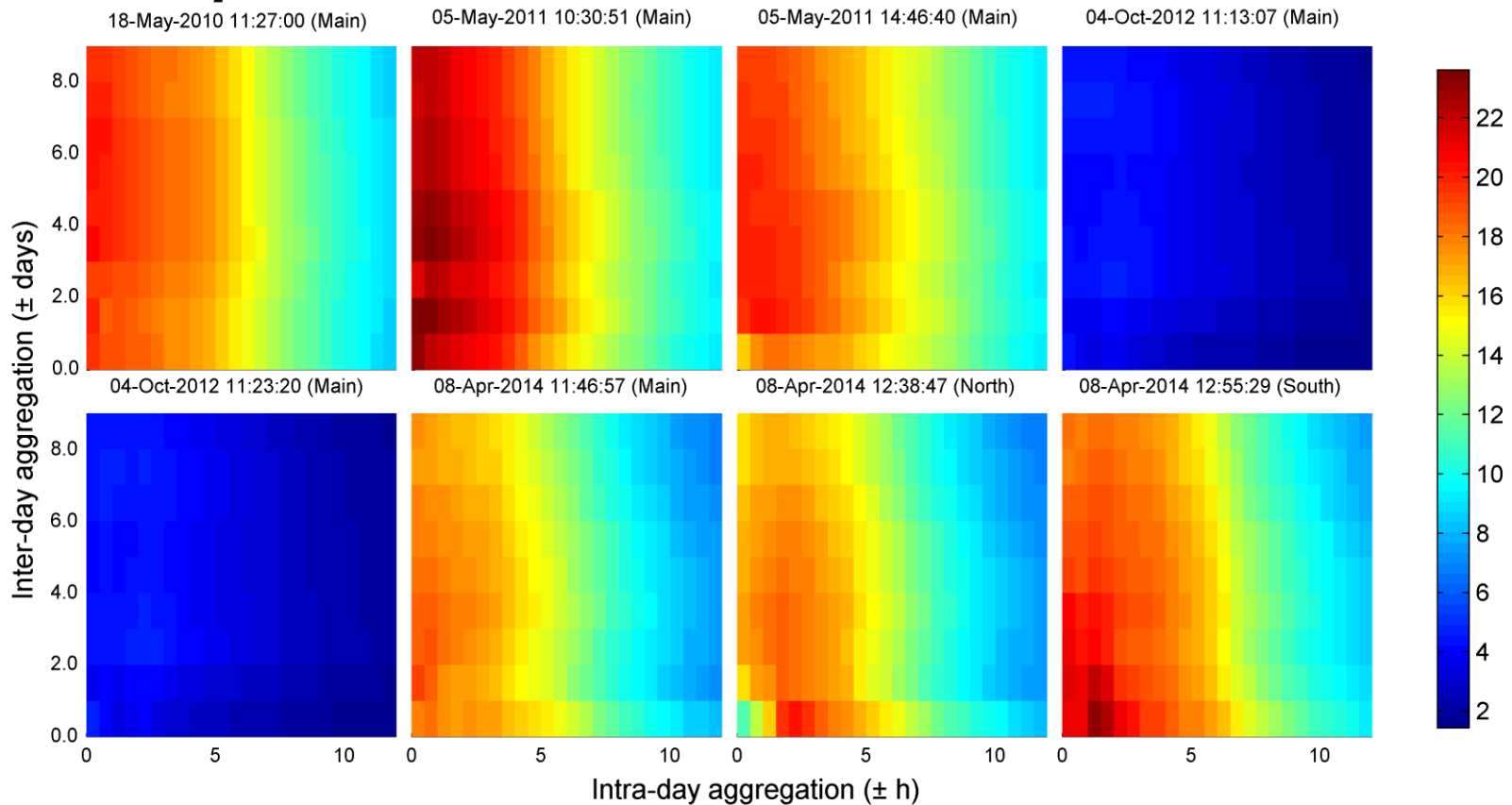




## 2. Methods

- Eddy Covariance Data

GPP ( $\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$ )(Full aggregation)



## 2. Methods

- Selection of different areas for pixel extraction
  - Modis pixels (centered)
    - 250 m
    - 500 m
  - Footprint analysis PDFs
    - Corresponding to the periods of EC data aggregation
    - Work in progress...



## 2. Methods

- GPP Models

- $GPP = \varepsilon \times fPAR \times PAR$  (Monteith 1972,1977)

- Model 1:  $GPP = a + b \times SVI$

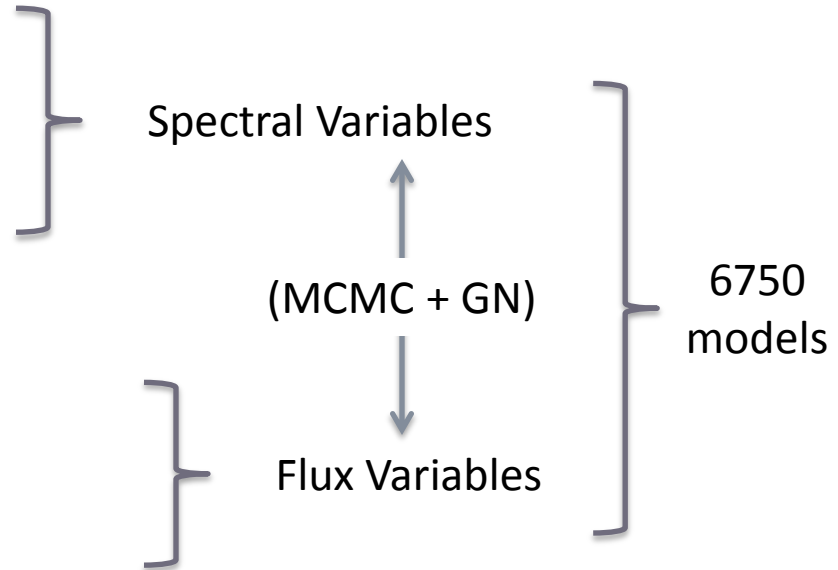
- Model 2:  $GPP = (a + b \times SVI) \times PAR$

- Model 3:  $GPP = (a + b \times SVI) \times (c + d \times \varepsilon) \times PAR$



## 2. Methods

- Data integration
  - Each model
    - Each sampling area type
      - Grass
      - Grass & Trees
      - All
    - Intra-day ( $\pm 12$  h)
    - Inter-day ( $\pm 9.5$  d)



## 2. Methods

- Spectral Vegetation Indices

$$NDVI = \frac{\rho_{800} - \rho_{680}}{\rho_{800} + \rho_{680}}$$

$$RDVI = \frac{\rho_{800} - \rho_{670}}{\sqrt{\rho_{800} + \rho_{670}}}$$

$$\text{Vogelmann 1} = \frac{\rho_{740}}{\rho_{720}}$$

$$EVI = 2.5 \times \frac{\rho_{858} - \rho_{645}}{\rho_{858} + 6 \times \rho_{645} - 7.5 \times \rho_{469} + 1}$$

$$TCARI/OSAVI = \frac{3 \times \left[ (\rho_{700} - \rho_{670}) - 0.2 \times (\rho_{700} - \rho_{550}) \times \frac{\rho_{700}}{\rho_{670}} \right]}{(1 + 0.16) \times (\rho_{800} - \rho_{670}) / (\rho_{800} + \rho_{670} + 0.16)}$$

- Light Use Efficiency

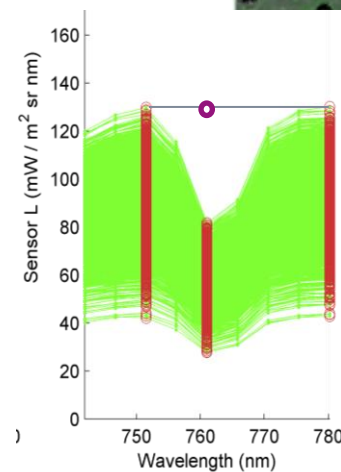
$$PRI = \frac{\rho_{531} - \rho_{570}}{\rho_{531} + \rho_{570}}$$

- PAR: global radiation



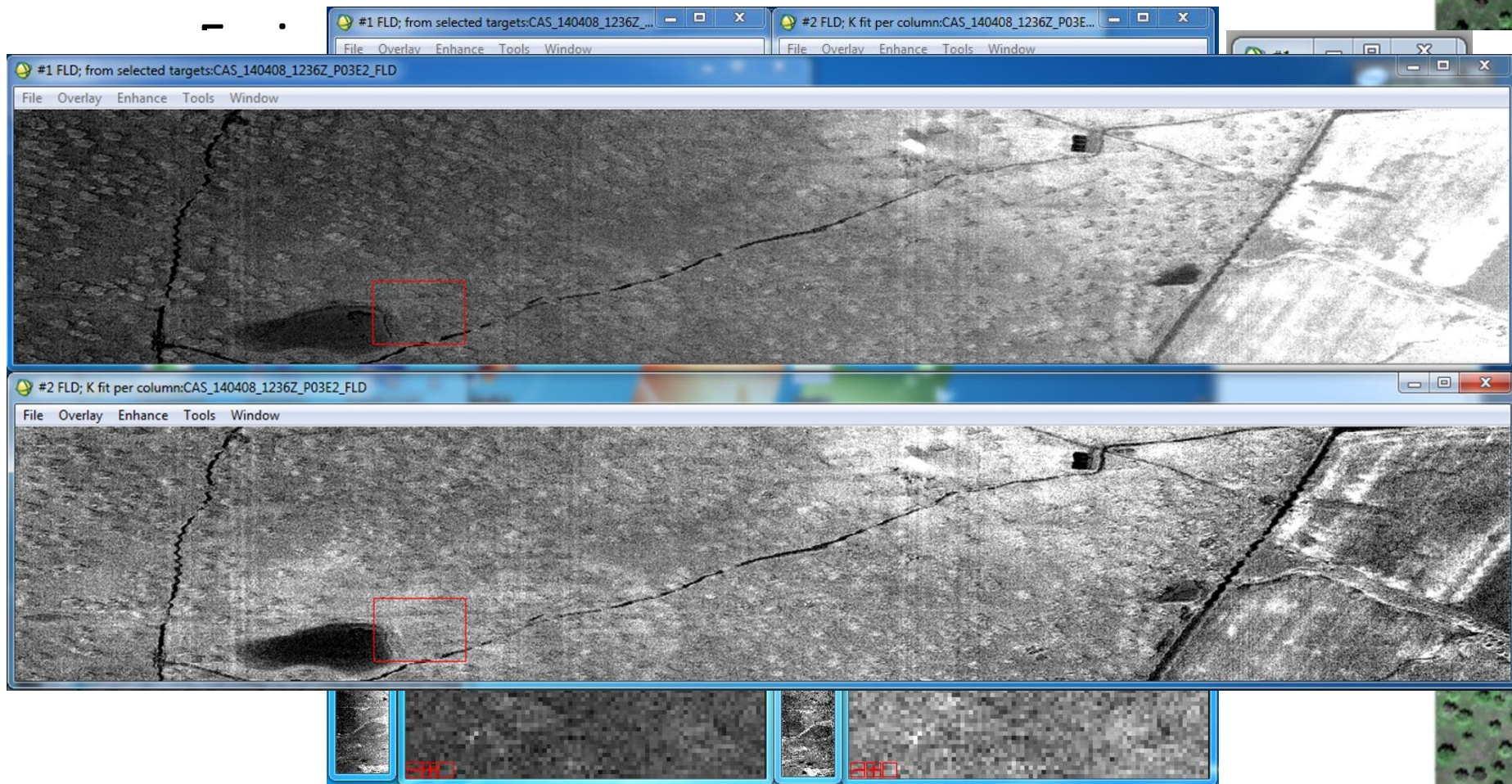
# 3. Estimation of Sun Induced Fluorescence

- University of Milano-Bicocca
  - Micol Rossini (& Pablo Zarco-Tejada)
  - Fluxpec Stay + STMS (Cost Action Optimise)
- Attempt to retrieve SIF (~LUE)
  - FLD & 3FLD
  - Non-fluorescent targets:  $L_i = k_1 L_o + k_2$
  - $F_{760}$  retrieval:  $k_3 L_f = L_i - (k_1 L_o + k_2)$



# 3. Estimation of Sun Induced Fluorescence

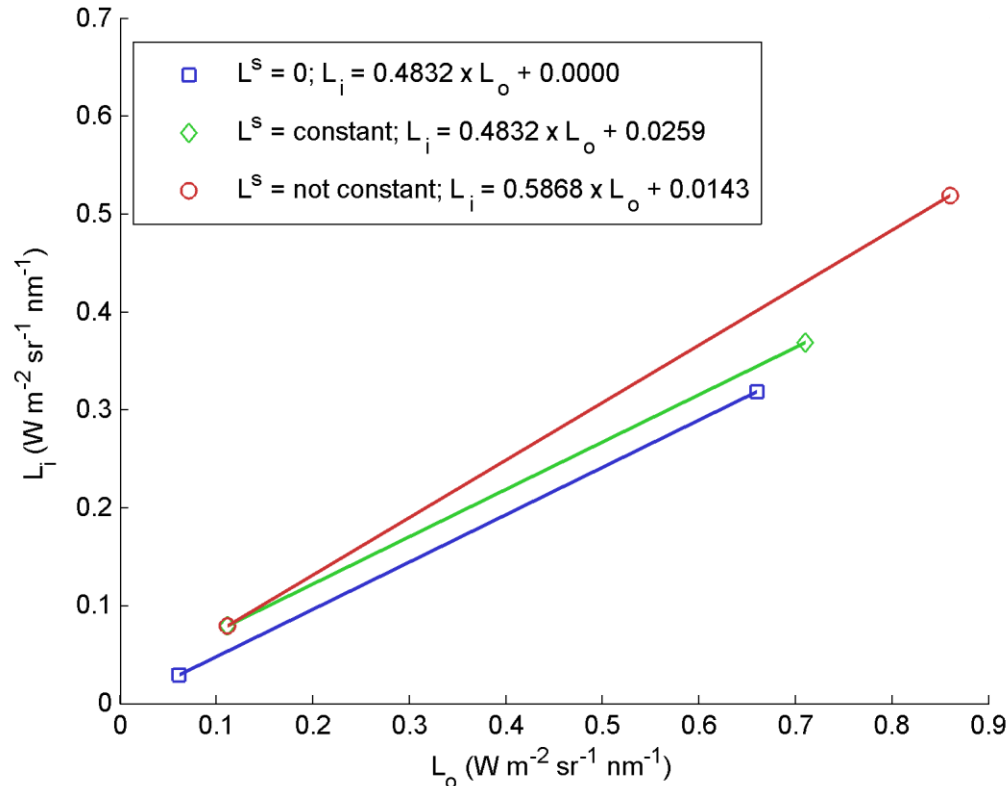
- Problems  $F_{760}$  retrieval





# 3. Estimation of Sun Induced Fluorescence

- Bias formulation (from Maier et al. (2002))



Further details in the STMS report.

Should be published soon in:  
<http://optimise.dcs.aber.ac.uk/tsms/>



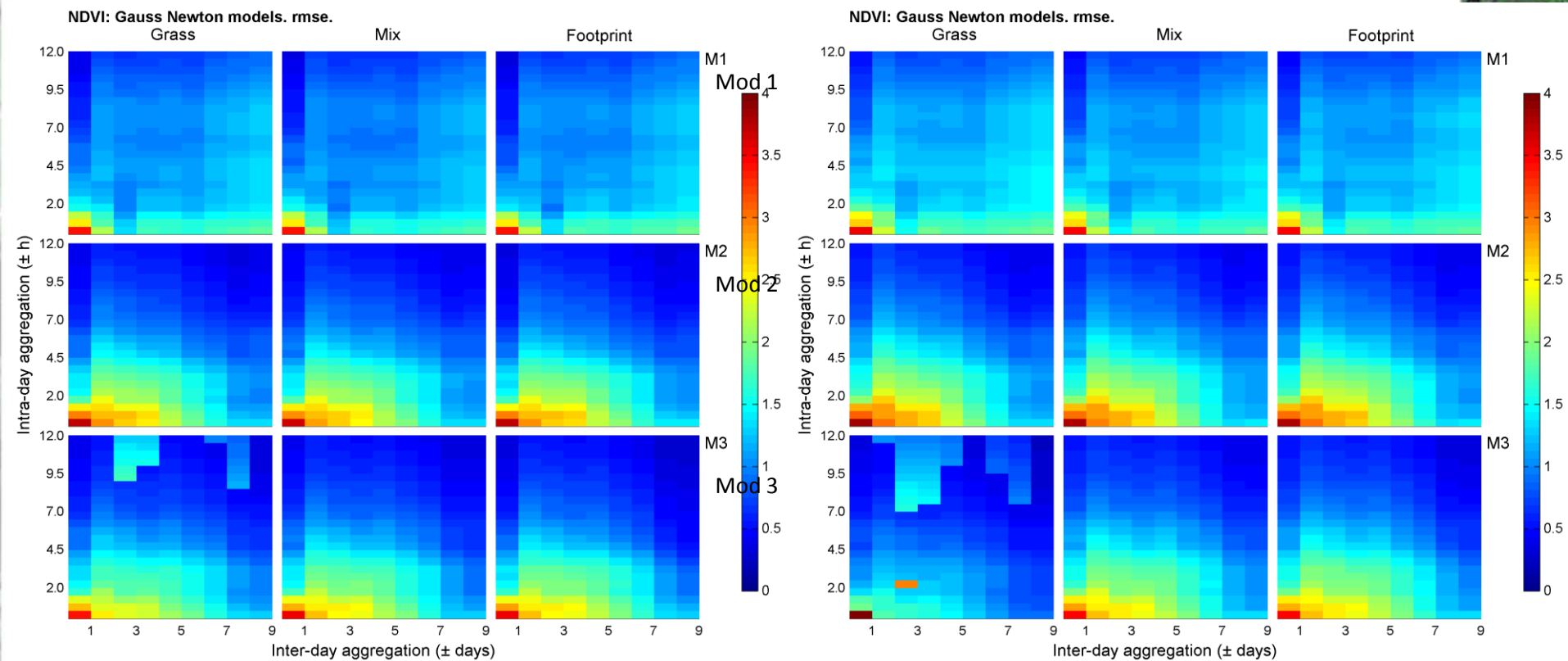
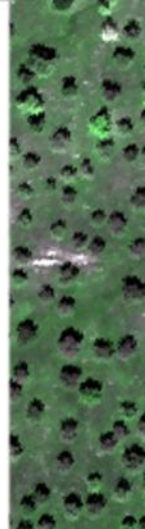
Biased coefficients  
actually adjusted



# 4. Results

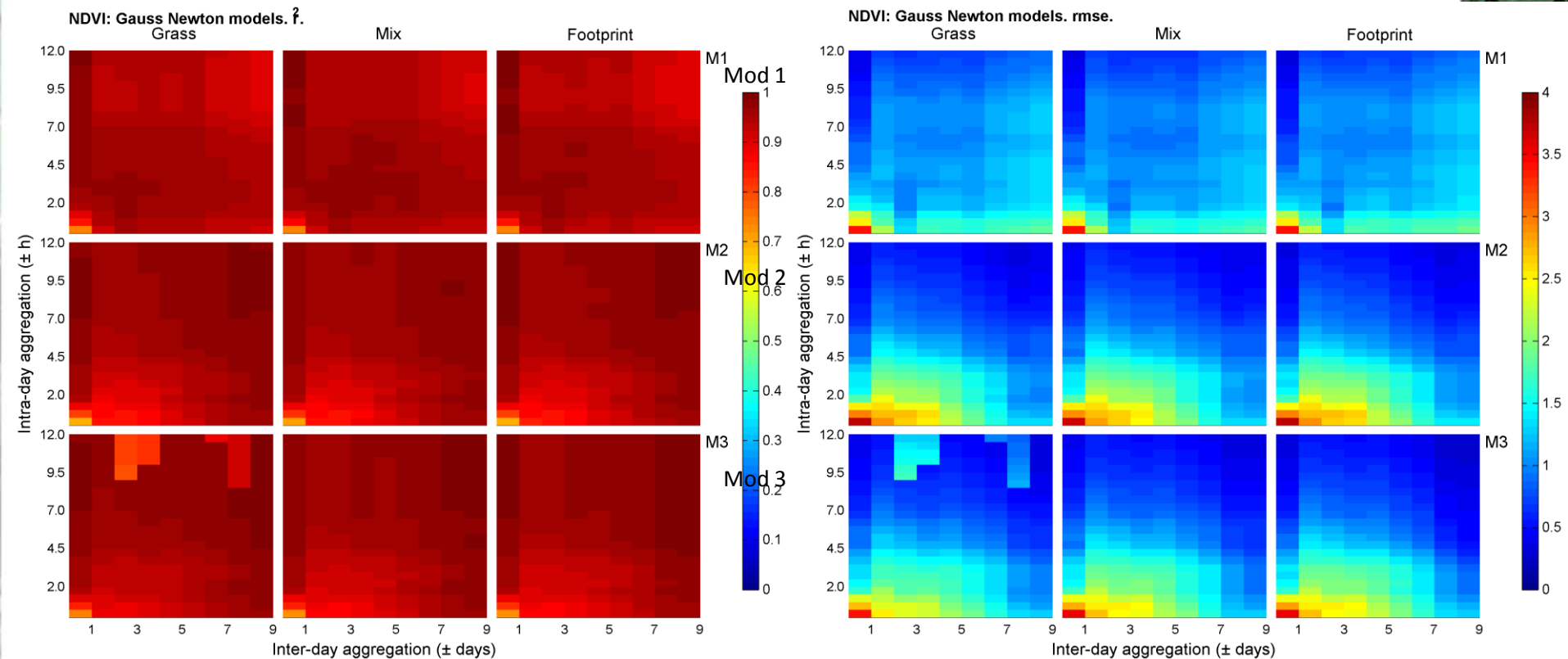
250 m x 250 m

500 m x 500 m

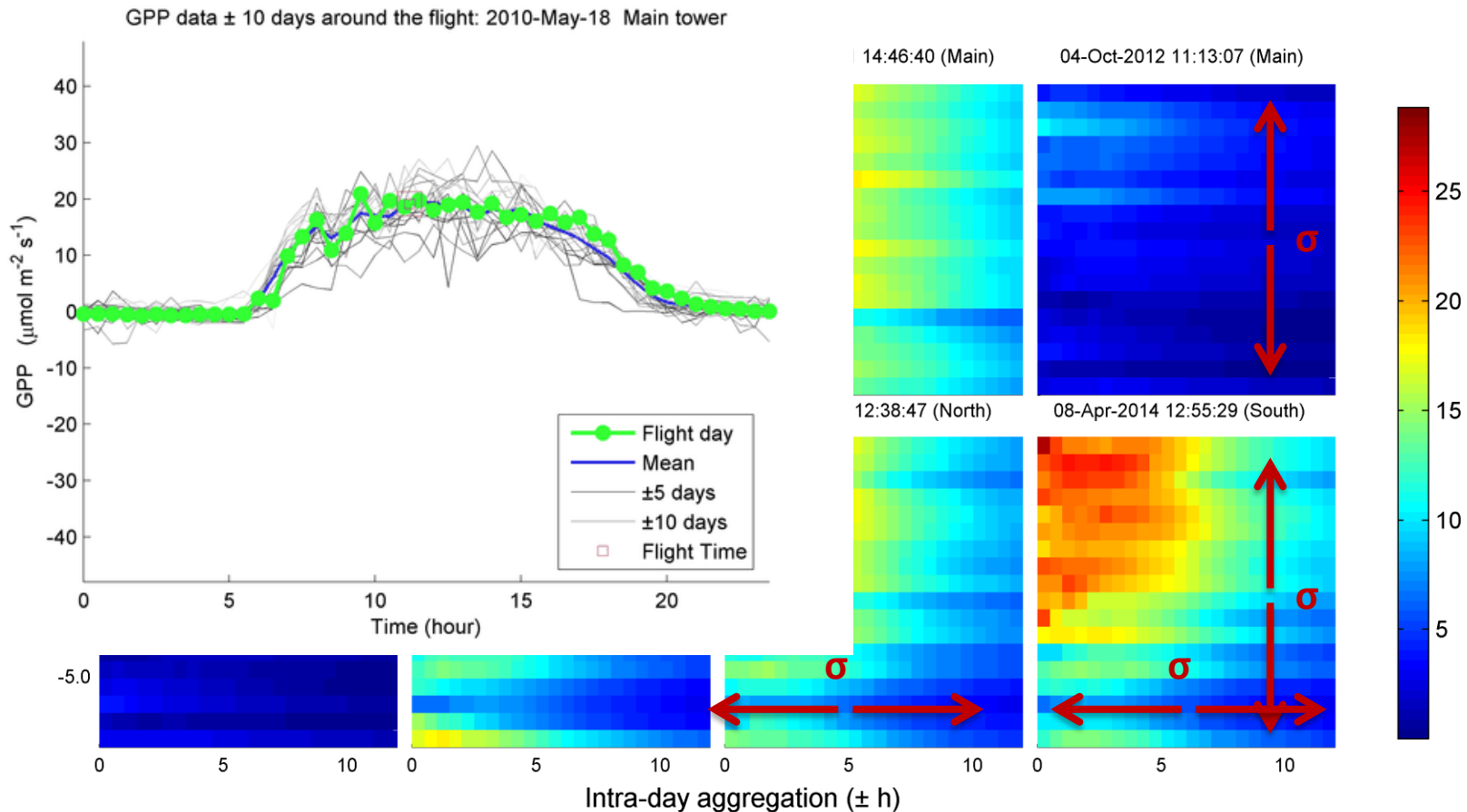


# 4. Results

- Relationships in the time domain



- Understanding errors



# 5. Preliminar discussion

- No large differences with simulated MODIS pixels
  - Footprint analysis: to be done...
- Spectral mixture
  - Mix of vegetation spectra do not improves estimates (different relationships)
  - Non-vegetated cover slightly increase errors



# 5. Preliminar discussion

- Temporal aggregation of flux data
  - In general, daily averages and averages of more several days are better predicted than instantaneous GPP
- Model used
  - Including radiation improves estimation further from the flight
  - PRI does not always lead to better results





Questions & suggestions?

*THANKS!!!*